



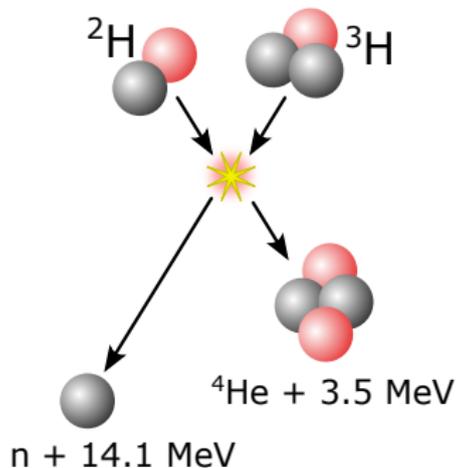
Adjoint Monte Carlo particle methods with reversible random number generators

E. Løvbak, G. Samaey

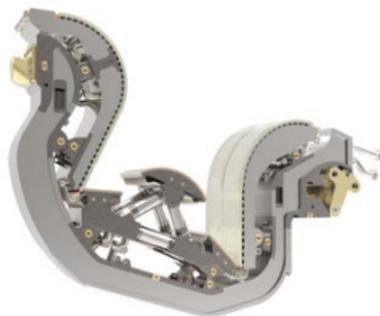
F. Blondeel, A. Lee, L. Vanroye, A. Van Barel, S. Vandewalle

KU Leuven, Department of Computer Science, NUMA Section

Motivation: nuclear fusion in tokamaks



Proton 
Neutron 



$Q \geq 10$: 50MW \rightarrow 500MW



china eu india japan korea russia usa

Didactical example: Heat equation in 1D

► Macroscopic view

$$\frac{\partial}{\partial t} \mathcal{T}(x, t) - \frac{\partial^2}{\partial x^2} \mathcal{T}(x, t) + u(x) \mathcal{T}(x, t) = 0$$

► Particle view

$$\{Q_{p,\tau}\}_{p=1}^P = \left\{ \left[\begin{array}{c} X_{p,\tau} \\ W_{p,\tau} \end{array} \right] \right\}_{p=1}^P, \quad \tau = 0, \dots, T-1$$

- Diffusion step

$$X_{p,\tau+1} = X_{p,\tau} + \sqrt{2\Delta t} \xi_{p,\tau} \quad \xi_{p,\tau} \sim \mathcal{N}(0, 1)$$

- Reweighting step

$$W_{p,\tau+1} = W_{p,\tau} \exp(-\Delta t \hat{u}(X_{p,\tau+1}))$$

Optimization problem

► Continuous

$$\min_{u(x)} \mathcal{J}(\mathcal{T}(x, t), u(x, t)) = \int_0^\infty \int_0^L \frac{1}{2} \mathcal{T}(x, t)^2 dx dt + \kappa \int_0^L \frac{1}{2} u(x)^2 dx$$

$$\text{subject to } \frac{\partial}{\partial t} \mathcal{T}(x, t) - \frac{\partial^2}{\partial x^2} \mathcal{T}(x, t) + u(x) \mathcal{T}(x, t) = 0,$$

$$\mathcal{T}(x, 0) = \mathcal{T}_0(x), \quad \mathcal{T}(0, t) = \mathcal{T}(L, t)$$

► Discrete

$$\mathcal{J}(\mathcal{T}(x, t), u(x, t)) \approx \hat{\mathcal{J}}(\hat{\mathcal{T}}, \hat{u}) = \Delta t \sum_{\tau=0}^T \Delta x \frac{1}{2} \hat{\mathcal{T}}_\tau^\top \hat{\mathcal{T}}_\tau + \nu \Delta x \frac{1}{2} \hat{u}^\top \hat{u}$$

$$\hat{\mathcal{T}}_{\tau, n} = \sum_{p=1}^P \frac{1}{\Delta x} \mathcal{I}_n(X_{p, \tau}) W_{p, \tau}$$

Adjoint-based optimization

- ▶ PDE-constrained optimization

$$\min_u \mathcal{J}(q, u), \quad \text{subject to} \quad \mathcal{B}(q; u) = 0$$

- ▶ Naive application of chain rule

$$\frac{d\mathcal{J}}{du}(q(u), u) = \frac{\partial \mathcal{J}}{\partial u}(q, u) + \frac{\partial \mathcal{J}}{\partial q}(q, u) \frac{dq}{du}(u)$$

Adjoint-based optimization

- ▶ PDE-constrained optimization

$$\min_u \mathcal{J}(q, u), \quad \text{subject to} \quad \mathcal{B}(q; u) = 0$$

- ▶ Naive application of chain rule

$$\frac{d\mathcal{J}}{du}(q(u), u) = \frac{\partial \mathcal{J}}{\partial u}(q, u) + \frac{\partial \mathcal{J}}{\partial q}(q, u) \frac{dq}{du}(u)$$

Adjoint-based optimization

- ▶ PDE-constrained optimization

$$\min_u \mathcal{J}(q, u), \quad \text{subject to} \quad \mathcal{B}(q; u) = 0$$

- ▶ Naive application of chain rule

$$\frac{d\mathcal{J}}{du}(q(u), u) = \frac{\partial \mathcal{J}}{\partial u}(q, u) + \frac{\partial \mathcal{J}}{\partial q}(q, u) \frac{dq}{du}(u)$$

- ▶ Solution: Lagrangian $\mathcal{L}(q, q^*, u) = \mathcal{J}(q, u) + (q^*, \mathcal{B}(q, u))$

$$\mathcal{B}(q, u) = 0 \quad \text{State equation}$$

$$\frac{\partial \mathcal{J}^*}{\partial q}(q, u) + \frac{\partial \mathcal{B}^*}{\partial q}(q, u) q^* = 0 \quad \text{Adjoint equation}$$

$$\frac{\partial \mathcal{J}^*}{\partial u}(q, u) + \frac{\partial \mathcal{B}^*}{\partial u}(q, u) q^* = 0 \quad \text{Design equation}$$

Discrete adjoint

- ▶ Linearized discretization around $\hat{q}' = \hat{q}(\hat{u})$

$$\hat{\mathcal{B}}(\hat{q}, \hat{u}) \approx \hat{\mathcal{B}}(\hat{q}', \hat{u}) + \frac{\partial \hat{\mathcal{B}}}{\partial \hat{q}}(\hat{q}', \hat{u})(\hat{q} - \hat{q}') = 0$$

is a matrix-vector system

Discrete adjoint

- ▶ Linearized discretization around $\hat{q}' = \hat{q}(\hat{u})$

$$\hat{\mathcal{B}}(\hat{q}, \hat{u}) \approx \frac{\partial \hat{\mathcal{B}}}{\partial \hat{q}}(\hat{q}', \hat{u})(\hat{q} - \hat{q}') = 0$$

is a matrix-vector system

- ▶ Adjoint equation

$$\frac{\partial \hat{\mathcal{J}}}{\partial \hat{q}}(\hat{q}', \hat{u})^\top + \frac{\partial \hat{\mathcal{B}}}{\partial \hat{q}}(\hat{q}', \hat{u})^\top \hat{q}^* = 0$$

Adjoint Monte Carlo

- ▶ Simulate particles from final state

$$Q_{p,T}^* = \begin{bmatrix} X_{p,T}^* \\ W_{p,T}^* \end{bmatrix} = -\frac{\partial \hat{\mathcal{J}}^\top}{\partial Q_{p,T}} = -\begin{bmatrix} 0 \\ \Delta t \hat{\mathcal{T}}(X_{p,T}) \end{bmatrix}$$

- ▶ Reverse time stepping

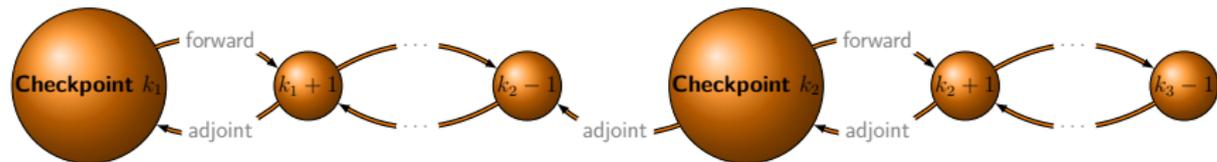
$$\begin{aligned} Q_{p,\tau}^* &= -\frac{\partial B_{p,\tau+1}^\top}{\partial Q_{p,\tau}} Q_{p,\tau+1}^* - \frac{\partial \hat{\mathcal{J}}^\top}{\partial Q_{p,\tau}} \\ &= \begin{bmatrix} X_{p,\tau+1}^* \\ \exp(-\Delta t \hat{u}(X_{p,\tau+1})) W_{p,\tau+1}^* \end{bmatrix} - \begin{bmatrix} 0 \\ \Delta t \hat{\mathcal{T}}(X_{p,\tau}) \end{bmatrix} \end{aligned}$$

- ▶ Note that $X_{p,\tau}^* = 0$ for all τ

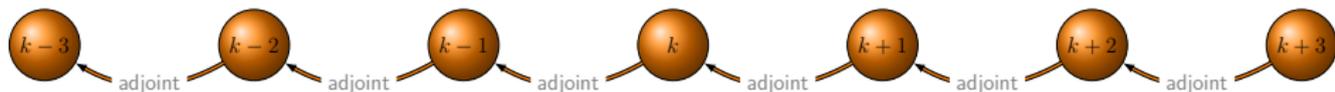
$$W_{p,\tau}^* = \exp(-\Delta t \hat{u}(X_{p,\tau+1})) W_{p,\tau+1}^* - \Delta t \hat{\mathcal{T}}(X_{p,\tau})$$

Matching forward and adjoint simulations

- ▶ Same paths in forward/backward simulation
- ▶ Challenge: $P \times T$ large
- ▶ Solutions:
 - Checkpointing: 2 forward simulations + backward simulation



- Generating the paths in reverse (this work)



Reversing a random number generator

▶ PCG: permuted congruential generator¹

- internal state ζ_k and constant vectors a, c, m

$$\zeta_{k+1} = a\zeta_k + c \pmod{m},$$

- 1-way (permutation) function generates output from ζ_k
- Passes TestU01 with flying colors

▶ Reversing modular operations \rightarrow reversed uniform sequence

$$\zeta_k = a^{-1}(\zeta_{k+1} - c) \pmod{m},$$

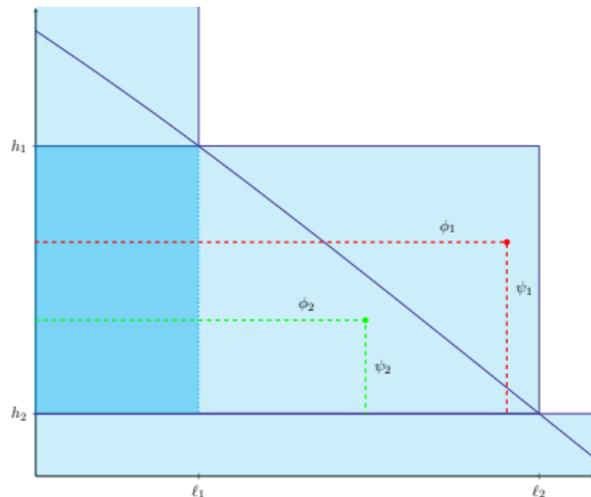
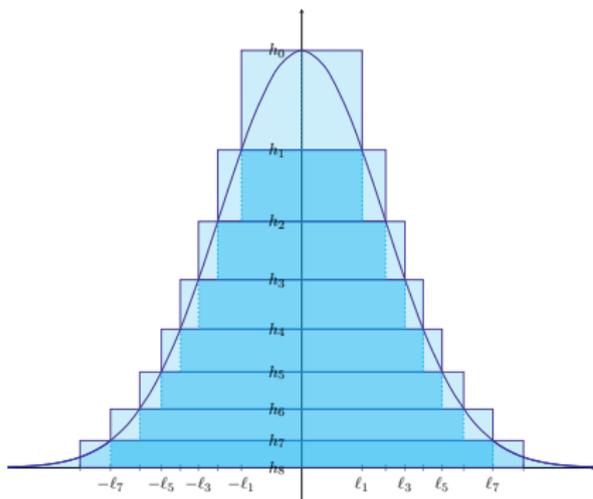
$$a^{-1} \equiv a^{m-2} \pmod{m}$$

▶ Exponential distribution through inverse transform:

$$u \sim \mathcal{U}([0, 1]) \Rightarrow -\lambda \ln(1 - u) \sim \mathcal{E}(\lambda)$$

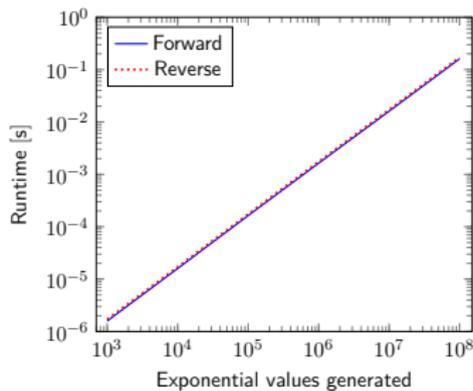
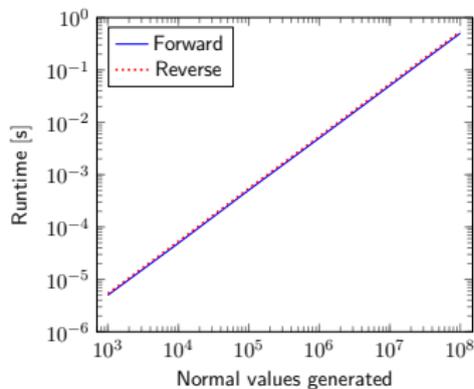
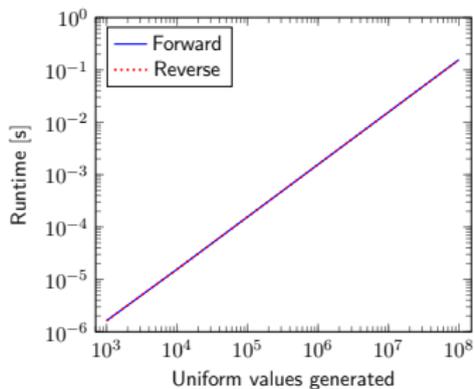
1: M.E. O'Neill, *PCG: A Family of Simple Fast Space-Efficient Statistically Good Algorithms for Random Number Generation*. Technical report HMC-CS-2014-0905, Harvey Mudd College (2014)

Normal distribution through Ziggurat

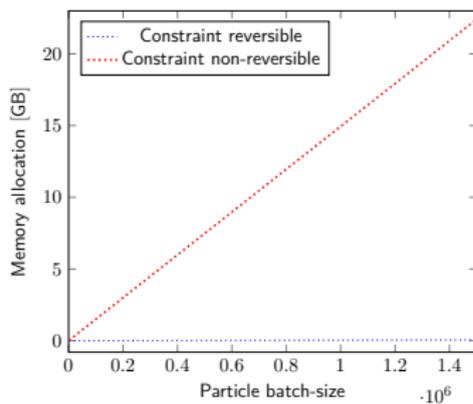
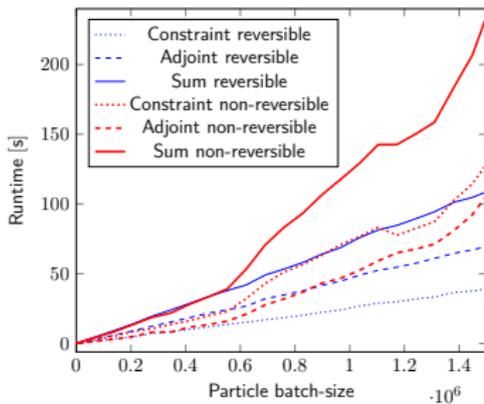
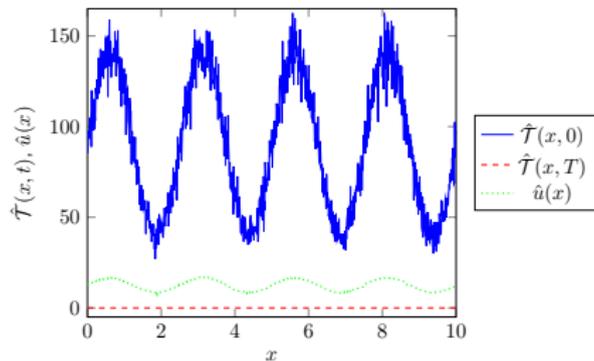


- ▶ Uses either 1, 2 or $1 + 2n$, $n = 1, 2, \dots$ uniform values
- ▶ How many depends on the first value
- ▶ Solution: Seed second generator

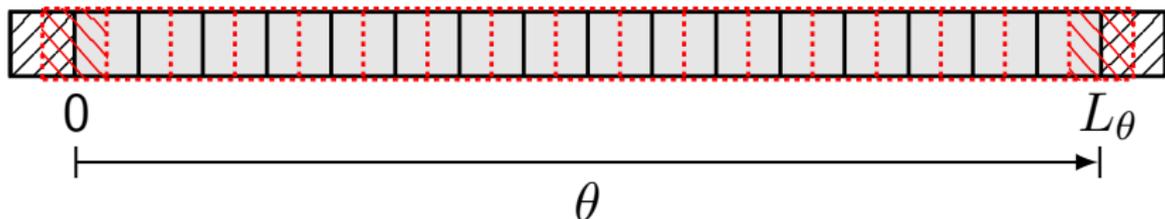
Generator timings



Optimal cooling



Fusion example: domain length optimization²



$$\mathcal{J}(q, L_\theta) = \frac{1}{2} \left(n_i b_\theta u_{\parallel} - \Gamma_d \right)^2 \Big|_{L_\theta} + \frac{\kappa}{2} (L_\theta - L_0)^2$$

$$q = \left(n_i, u_{\parallel}, f_n \right)^\top$$

- n_i plasma density
- u_{\parallel} plasma velocity
- f_n neutral position-velocity

Plasma edge model

- ▶ Plasma \Rightarrow Finite volume

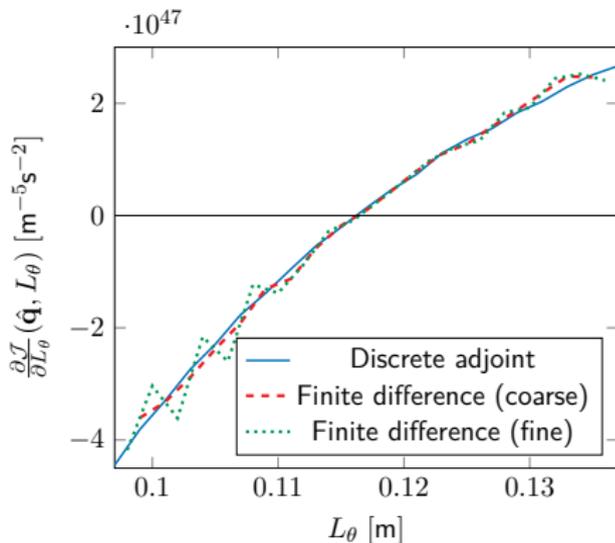
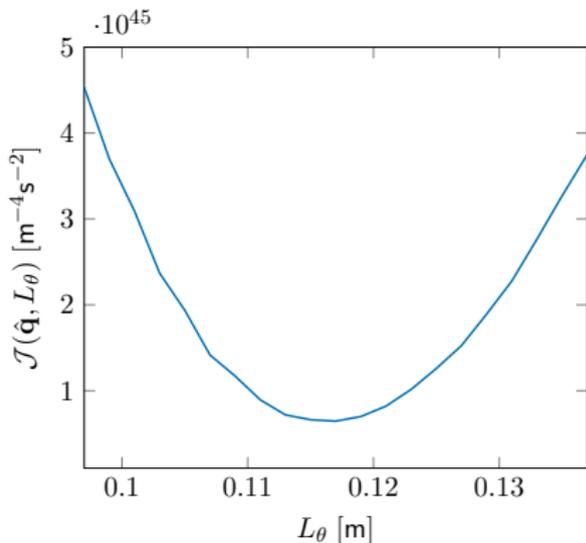
$$\frac{\partial}{\partial \theta} \left(n_i b_\theta u_{\parallel} \right) = S_{n_i} - K_d n_i$$
$$\frac{\partial}{\partial \theta} \left(m n_i b_\theta u_{\parallel}^2 - \nu_d \frac{\partial u_{\parallel}}{\partial \theta} \right) = S_{u_{\parallel}} - b_\theta \frac{\partial p}{\partial \theta}$$

$$S_\psi = \int f_{\mathbf{n}}(\theta, v) \Psi(\theta, v) dv, \quad \psi \in \{n_i/u_{\parallel}\} \quad \Rightarrow \quad \text{Low-dimensional}$$

- ▶ Neutrals \Rightarrow Monte Carlo

$$v \frac{\partial}{\partial \theta} f_{\mathbf{n}}(\theta, v) + K_i f_{\mathbf{n}}(\theta, v) = S_{f_{\mathbf{n}}}(n_i, u_{\parallel}) + K_{cx} \int f_{\mathbf{n}}(\theta, v') C(v' \rightarrow v) dv'$$

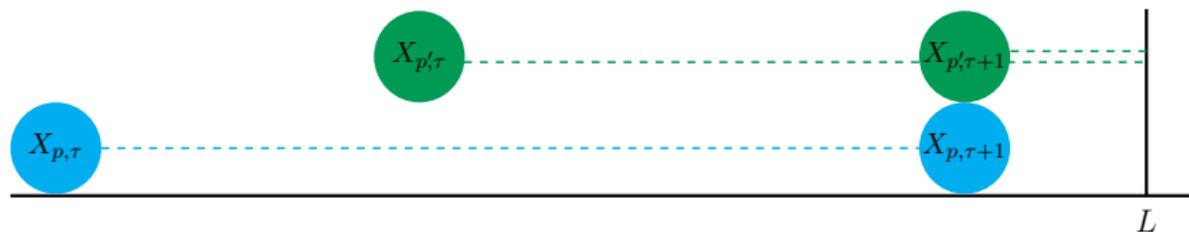
Preliminary results



	n_i -solver	$u_{ }$ -solver	Neutral solver
State	3.5×10^{-5} s	4.1×10^{-5} s	6.6 s
Adjoint	3.1×10^{-5} s	3.6×10^{-5} s	9.8 s

Can all simulations be reversed?

- ▶ In theory yes!
- ▶ ... but at what cost?
 - Reflections
 - Collisions in batched simulations
 - ...



Løvnbak, E., Blondeel, F., Lee, A., Vanroye, L., Van Barel, A., Samaey, G., *Reversible random number generation for adjoint Monte Carlo simulation of the heat equation*. Monte Carlo and Quasi-Monte Carlo Methods - MCQMC 2022. Submitted (2023) [arXiv:2302.02778](https://arxiv.org/abs/2302.02778)

Løvnbak, E., *Multilevel and adjoint Monte Carlo methods for plasma edge neutral particle models*. PhD thesis (2023)